

# Matthew Sanetra

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## Education

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### **Bachelor's, Computer Science**, University of Oxford Oct 2022 - Paused

- Computer Science subject representative.
  - Key contact between students and department staff.
  - Ensuring feedback and changes improve outcomes for future students.
- Societies: Rowing, Robotics and Additive Manufacturing, Rocketry.
- Currently paused studies due to familial matters.

### **A Levels**, Hammersmith Academy Sept 2020 - Aug 2022

- Grades: A\*A\*AB in Computer Science, Maths, Further Maths, Physics.
  - Member of the Sixth Form Leadership Team.
    - Began a successful initiative to reform the dress-code and lateness policy.
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## Experience

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### **Sales Associate**, Oddono's Gelati Italiani July 2022 - Sept 2022

- Demonstrated the ability to serve customers in the busiest shop on Chiswick High Road (>£2000 daily gross revenue, peak ≈£7000).
  - Created end-of-day reports, handled cash register accounting, took deliveries, opened and closed shop.
  - Loved working with people, gaining valuable experience working in a tight-knit and highly organised team.
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## Projects

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### **Gana**, [thecsw/gana](#) Nov 2022 - Present

- Core contributor to a Go generics library
- Used internally (in a limited fashion) at Microsoft.

### **Rocket Guidance Computer**, in *Kerbal Space Program* July 2020 - Present

- Currently developing a compiler for my own domain-specific language with the Rust programming language, targeting kOS Machine Code.
- Developed rocket guidance that recreates a SpaceX Starship landing.
  - [Video 1](#), [Video 2](#)

### **Self-Driving Car**, funded by the Mark Evison Foundation May 2021 - Sept 2021

- Collaborated in a group of 6.
- Implemented a test harness to allow simulating and testing the Raspberry Pi and the immediate surrounding environment, enabling test-driven development of control algorithms.
- Programmed in Python, utilising OpenCV.

### **Racing Boat Autopilot**, IET Faraday Challenge Days May 2017 - July 2017

- Competition to develop a product to help the Land Rover BAR team win the America's Cup.
- Led a team of 6 to place first in the UK.
- Devised embedded software optimising and balancing speed gain and manual steering ability via sail orientation.